

CREATING A RDF KNOWLEDGEBASE FROM OPENSTREETMAP DATA

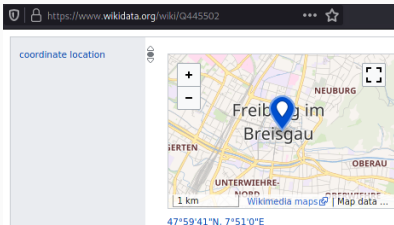
Axel Lehmann

Master's Thesis

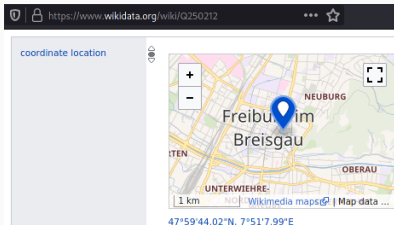
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- Query: All *places of worship* **with** *gothic architecture* **in** the *Altstadt of Freiburg*.
- Combine factual data with spatial constraints.
 - factual data provided by *Wikidata*.
 - spatial constraints provided by *OpenStreetMap*.

MOTIVATION — WIKIDATA



(a) Altstadt Freiburg coordinates



(b) Freiburg Minster coordinates

Figure 1: Point coordinates of *Altstadt Freiburg* (a) and *Freiburg Minster* (b) provided by Wikidata.

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MOTIVATION — OPENSTREETMAP

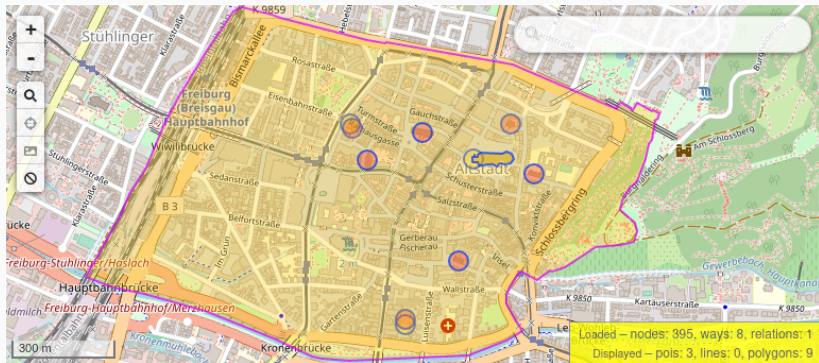


Figure 2: *Places of worship inside Altstadt Freiburg provided by Overpass.* © Overpass API; Base map and data from OpenStreetMap and OpenStreetMap Foundation

MOTIVATION — EXPECTED RESULT



Figure 3: Expected result for: All *places of worship with gothic architecture* in the Altstadt of Freiburg — The Freiburg Minster.

PROBLEM

- OpenStreetMap data not available as RDF
 - Sophox [Wik21] currently defunct
 - Jovanovik, Homburg, and Spasic [JHS21] found GeoSPARQL support in SPARQL engines to be lacking
- ⇒ Convert OpenStreetMap data into RDF Triples with explicit spatial relations

- Volunteers mapping the whole world.
- Generic information as key-value string pairs
- Spatial Entities
 - ≈ 6.5 B Nodes (Longitude, Latitude)
 - ≈ 0.7 B Ways (List of Nodes)
 - ≈ 8.3 M Relations (List of Nodes and ways with type information)
- Virtual Entities (libosmium)
 - ≈ 0.5 B Areas (Regions which can contain other elements, not explicitly stored, derived from ways and relations)
- Spatial relations (contains, intersects, etc.) not explicitly stored

- Describes knowledge as a graph
- Subject-Predicate-Object Triples
 - Predicates are edges in the knowledge graph
- N-Triples and Turtle dialects store all data as annotated strings

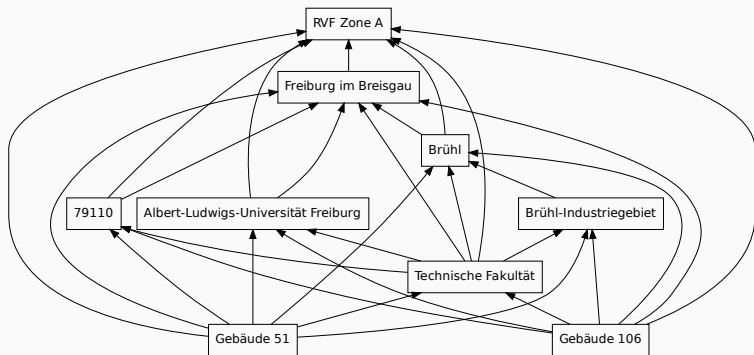
QUESTIONS?

APPROACH

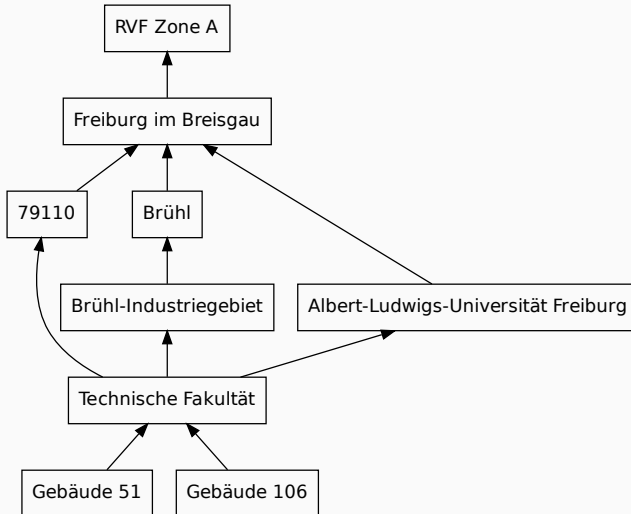
1. Convert key-value data into *RDF Triples*
 - Free form data → no structural guarantees
 - Multilingual (e.g. japanese) → UTF-8 support required
2. Conversion of spatial features into *well-known text*
 - Well-known text imposes stricter order requirements for elements
3. Calculating spatial relations and storing them as Triples
 - contains, intersects
 - Only tagged entities

APPROACH — SPATIAL AREA RELATIONS EXAMPLE

Spatial location of *Building 51* and *Building 106*



APPROACH — DIRECTED ACYCLIC GRAPH — I



Benefits:

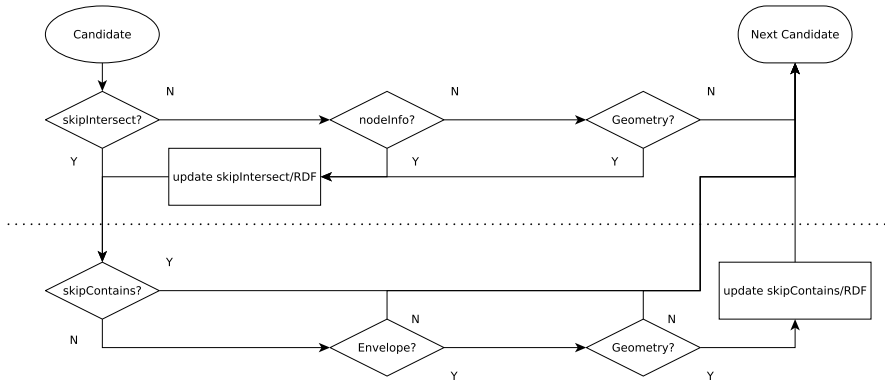
- Reduction of spatial comparisons
- Reduction of spatial triples (transitivity)

Problem:

- Where to look in the DAG?
R-tree as index structure → candidate ids based on envelope

APPROACH — SPATIAL RELATION CALCULATION — WAYS

Candidates from R-tree → check intersects and contains
(multithreaded using OpenMP)



QUESTIONS?

EXPERIMENTS

EXPERIMENTS — OVERVIEW

	freiburg	bawue	germany	europe	planet*
input (.pbf)	123 M	482 M	3.4 G	23 G	55 G[◦]
output (.bz2)	257 M	1.1 G	7.5 G	48 G	100 G*
ram usage	2.47 G	2.82 G	13.51 G	90.11 G	108 G [◊]
runtime facts	2.50 m	10.07 m	71.51 m	7.56 h	16.68 h
runtime geometry	50.13 s	44.96 m	15.30 h	12.28 d	47.02 d
runtime	3.34 m	55.02 m	16.49 h	12.59 d	47.72 d
fact triples	22.05 M	89.51 M	598.73 M	3.38 B	4.67 B
geometry triples [◊]	11.83 M	47.99 M	342.09 M	2.28 B	4.88 B

*Preliminary code used.

◦ Input contains metadata.

* 12 decimal places, no additional metadata.

◊ Node locations (during dump) stored on disk and not in RAM.

◊ Added relations in both directions.

EXPERIMENTS — OVERVIEW

	freiburg	bawue	germany	europa	planet*
nodes (src)	12.42 M	46.71 M	337.22 M	2.72 B	6.50 B
nodes (fact)	605.65 K	2.03 M	14.05 M	96.76 M	164.42 M
nodes (geom)	605.65 K	2.03 M	14.05 M	96.76 M	164.42 M
ways (s)	1.82 M	7.72 M	55.03 M	326.43 M	718.51 M
ways (f)	1.80 M	7.65 M	54.61 M	319.97 M	706.17 M
ways (g)	1.80 M	7.65 M	54.61 M	319.97 M	706.17 M
relations (s)	31.60 K	101.67 K	677.84 K	5.51 M	8.38 M
relations (f)	31.58 K	101.63 K	677.56 K	5.51 M	8.37 M
areas (s)	1.24 M	5.43 M	39.62 M	234.80 M	499.37 M
areas (f)	1.24 M	5.43 M	39.62 M	234.80 M	499.37 M
areas (g)	1.24 M	5.43 M	39.62 M	234.80 M	499.37 M

*Preliminary code used.

EXPERIMENTS — SPATIAL RELATION CALCULATIONS

		freiburg	bawue	germany	europe
DAG	vertices	32.79 K	146.46 K	991.31 K	5.54 M
	edges	40.19 K	181.20 K	1.23 M	7.69 M
unnamed area	\cap skipped (DAG)	60.94 K	272.69 K	1.61 M	14.95 M
	\cap	179.71 K	678.05 K	4.44 M	32.66 M
	\cap yes	56.37 K	213.19 K	1.48 M	7.61 M
	\subseteq skipped (DAG)	46.81 K	219.58 K	1.24 M	12.85 M
	\subseteq envelope	70.51 K	266.31 K	1.85 M	9.72 M
	\subseteq	19.84 K	59.89 K	398.03 K	4.76 M
	\subseteq yes	13.86 K	37.92 K	253.33 K	3.63 M
node	\subseteq skipped (DAG)	2.67 M	15.34 M	96.58 M	658.15 M
	\subseteq	3.54 M	17.68 M	118.04 M	903.54 M
	\subseteq yes	740.68 K	2.53 M	17.62 M	134.71 M

EXPERIMENTS — SPATIAL RELATION CALCULATIONS

		freiburg	bawue	germany	europa
DAG	vertices	32.79 K	146.46 K	991.31 K	5.54 M
	edges	40.19 K	181.20 K	1.23 M	7.69 M
way	in DAG	31.12 K	140.18 K	935.95 K	4.93 M
	\cap skipped (member)	109.72 K	535.81 K	4.32 M	23.28 M
	\cap skipped (DAG)	7.37 M	55.66 M	376.04 M	2.21 B
	\cap	10.37 M	66.95 M	453.93 M	2.98 B
	\cap yes	2.06 M	8.72 M	62.31 M	404.87 M
	\subseteq skipped (DAG)	7.19 M	54.80 M	370.28 M	2.18 B
	\subseteq envelope	2.35 M	10.11 M	72.40 M	461.92 M
	\subseteq	2.27 M	9.77 M	69.83 M	446.00 M
	\subseteq yes	2.11 M	9.04 M	64.95 M	418.67 M

CONCLUSION

CONCLUSION — FUTURE WORK

- Runtime
 - Spatial comparisons
 - better approximations (inner + outer shapes)
 - better index structure (R-tree axis aligned)
 - split areas with low area/envelope ratio
 - RDF / WKT
- OpenStreetMap relations
 - e.g. public transportation (Bus/Rail/Ferry)
- Spatial relations
 - touches, disjoint, ...
 - cardinal direction, distance ...

CONCLUSION — RESULT

- We provide OpenStreetMap data as RDF
- We enable non GeoSPARQL capable SPARQL engines to answer some spatial queries
 - intersects
 - contains
- DAG reduces number of explicit spatial relation triples
- Source code (GPLv3+):
<https://github.com/ad-freiburg/osm2ttl>
- Temporary demo:
https://qllever.cs.uni-freiburg.de/OSM_Test

QUESTIONS?

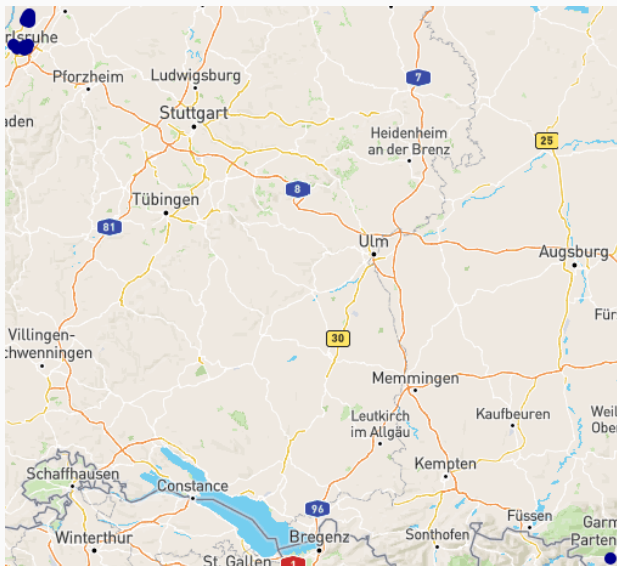


Milos Jovanovik, Timo Homburg, and Mirko Spasic. “A GeoSPARQL Compliance Benchmark”. In: *CoRR* abs/2102.06139 (2021). arXiv: 2102.06139. URL: <https://arxiv.org/abs/2102.06139>.

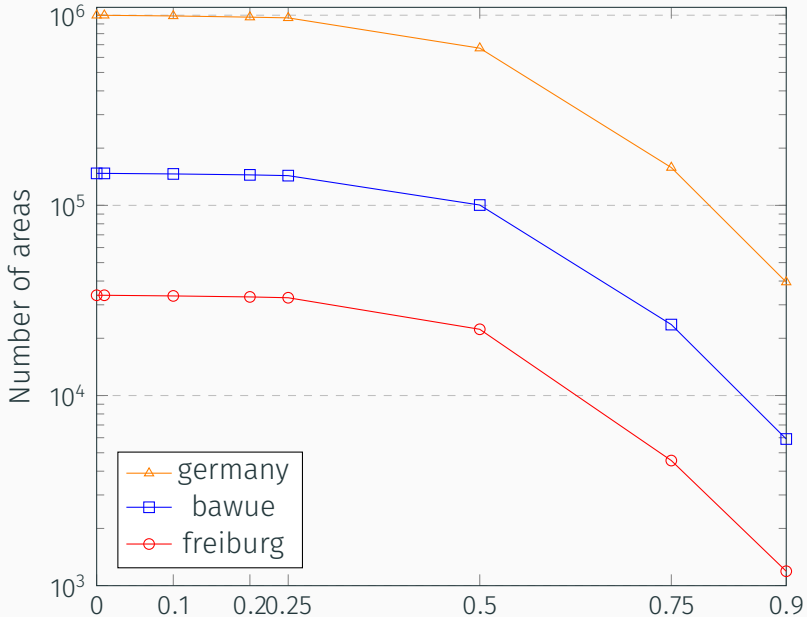


OpenStreetMap Wiki. *Sophox — OpenStreetMap Wiki*, [Online; accessed 15-March-2021]. 2021. URL: <https://wiki.openstreetmap.org/w/index.php?title=Sophox&oldid=2105584>.

AREA/ENVELOPE RATIO EXAMPLE



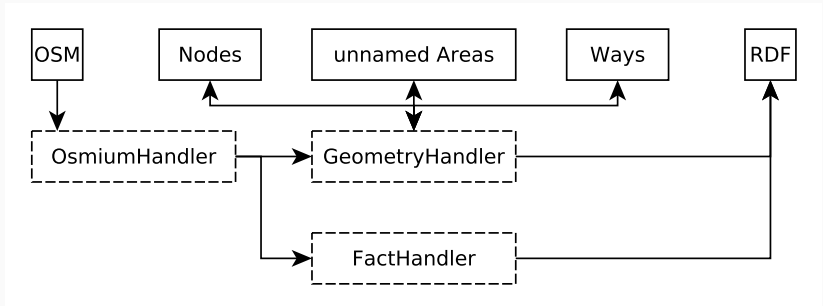
MINIMAL AREA/ENVELOPE RATIO



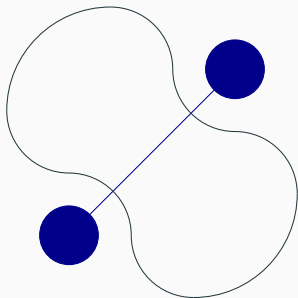
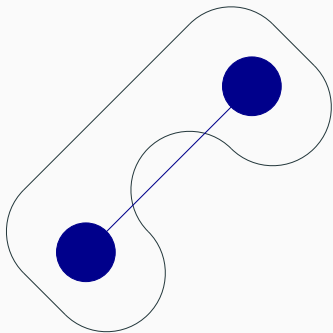
- Node (Single Point/Location)
POINT(x, y)
- Way
LINESTRING(x₀ y₀, x₁ y₁, ...)
- Area (solid, single part)
POLYGON((x₀ y₀, x₁ y₁, ...))
- Area (single part with holes)
POLYGON((x₀ y₀, x₁ y₁, ...), (...))
- Area (multiple parts with optional holes)
MULTIPOLYGON(((x₀ y₀, x₁ y₁, ...), (...)), (...))

- OpenStreetMap represents geometries explicit
 - Closed ways $(n_0, n_1, \dots, n_k) \mid n_0 = n_k$
 - Order and number of *inner* and *outer* not relevant
- WKT uses different representations
 - Closed ways as POLYGON (no repeat of first node)
 - Order of *inner* and *outer* is relevant
 - MULTIPOLYGON required for multiple *outer* parts

DATA FLOW



WHY EXPLICIT SPATIAL CALCULATIONS



SUB OPTIMAL INTERSECTION



Provided by: OpenStreetMap | Map data © OpenStreetMap contributors

The highlighted way crosses multiple administrative levels and intersects *Baden-Württemberg* and *Hesse*. It is contained in neither of them but in *Germany*.

- Gebäude 51
<https://www.openstreetmap.org/way/98284318>
- Gebäude 106
<https://www.openstreetmap.org/way/33903567>
- Technische Fakultät
<https://www.openstreetmap.org/way/4498466>
- Albert-Ludwigs-Universität Freiburg
<https://www.openstreetmap.org/relation/1590189>
- Brühl-Industriegebiet
<https://www.openstreetmap.org/relation/294855>
- Brühl
<https://www.openstreetmap.org/relation/1956119>

- 79110

<https://www.openstreetmap.org/relation/1112757>

- Freiburg im Breisgau

<https://www.openstreetmap.org/relation/62768>

- RVF Zone A

<https://www.openstreetmap.org/relation/4221993>